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L5	1349	(706/14 or 706/12 or 706/46) and @ad<"20030716"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/02/15 15:24
L6	359	computer and matrix and sparse and large and equation and sensor and control and @ad<"20030716"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2006/02/15 15:25
S1	7	"5654907"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/02/15 14:27
S2	2	"20040107012"	US-PGPUB; USPAT; EPO; JPO; DERWENT; IBM_TDB	OR	OFF	2006/02/15 12:25
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Digital Object Identifier 10.1109/ACSSC.2003.1292114
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Burgess, K.A.; Van Veen, B.D.; [Signals, Systems and Computers, 1994. 1994 Conference Twenty-Eighth Asilomar Conference on](#)

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- 5. **Unsupervised neural network learning for blind source separation**
Szu, H.; Hsu, C.;
Neural Networks, 1998. Proceedings. Vth Brazilian Symposium on
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- 6. **Proceedings of 2002 International Conference on Macrobionics and Cybernetics (Cat.No.02EX583)**
Machine Learning and Cybernetics, 2002. Proceedings. 2002 International Conference on
Volume 2, 4-5 Nov. 2002
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Supercomputing '90. Proceedings of
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MA Henson, DE Seborg - 1997 - Prentice-Hall
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 ... closed-loop trajectories of the nonlinear system due to ... As usual in predictive control
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 ... systems via receding horizon control Lyapunov functions M. S:nair and J. Cloutier
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R Findeisen, L Imsland, F Allgower, B Foss - LECTURE NOTES IN CONTROL AND INFORMATION SCIENCES, 2003 - Springer
 ... Summary. This paper considers the stability, robustness and output feedback problem for sampled-data nonlinear model predictive control (NMPC). ...
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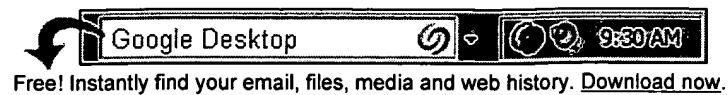
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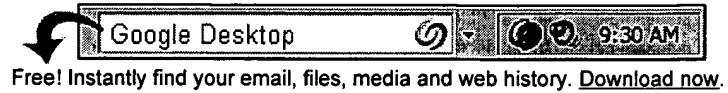
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